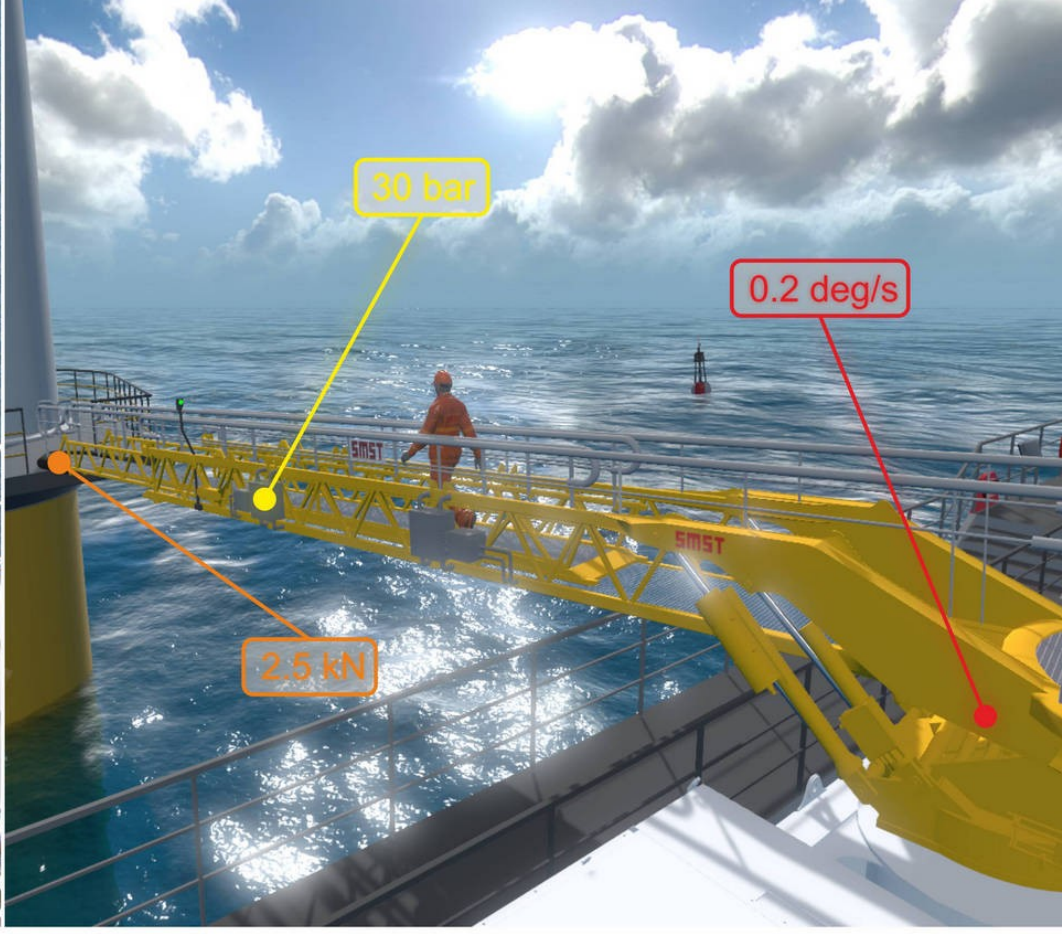
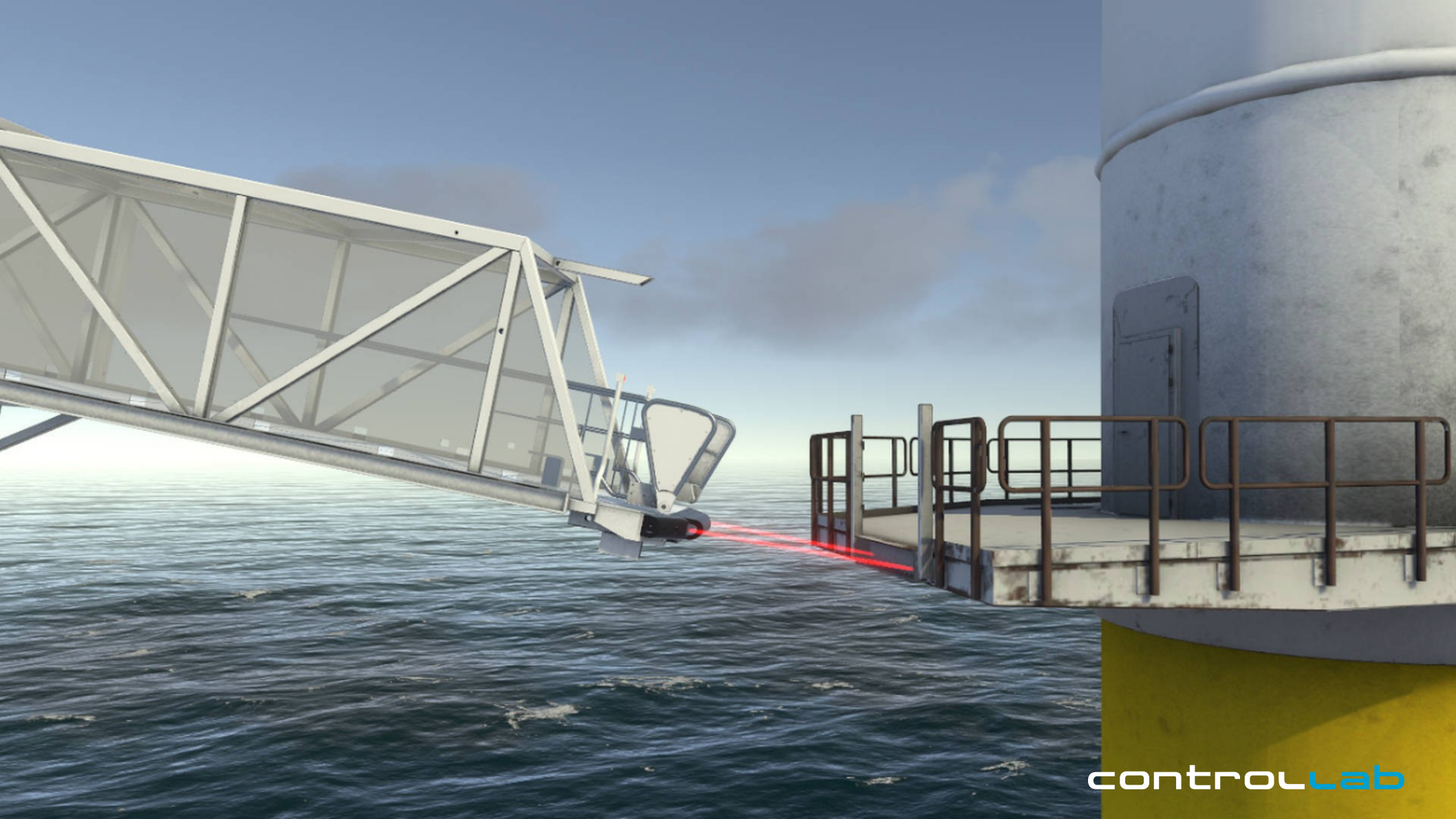

controllab

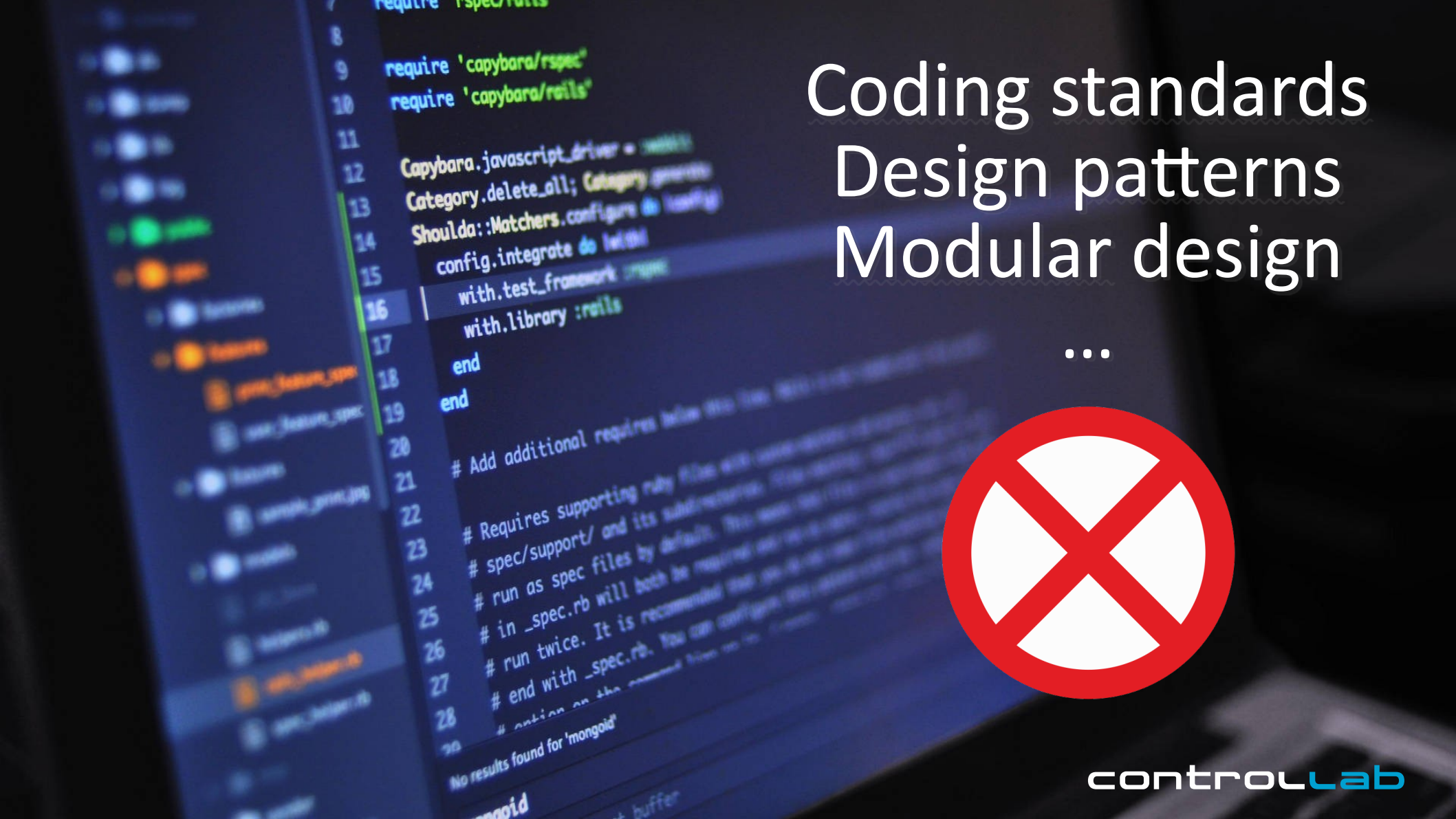


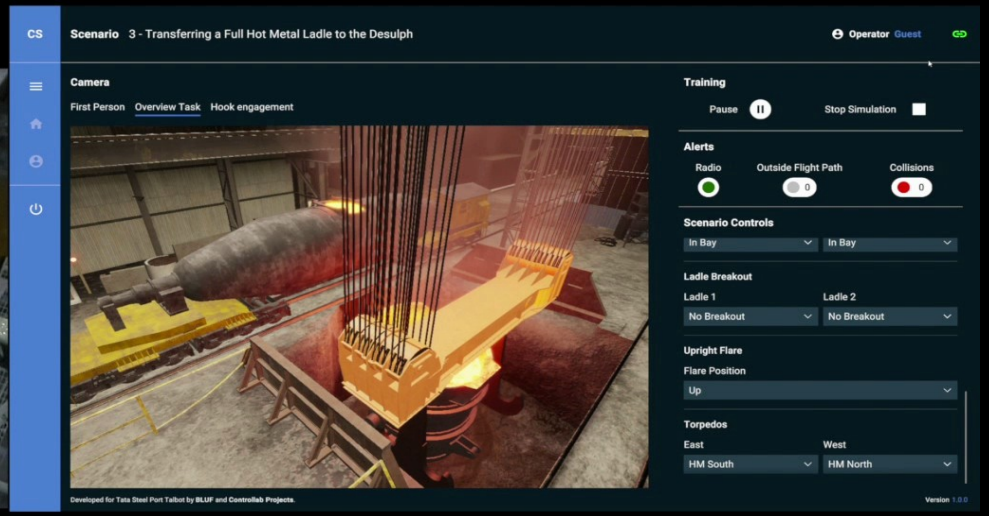
DIGITAL TWIN

controlLab

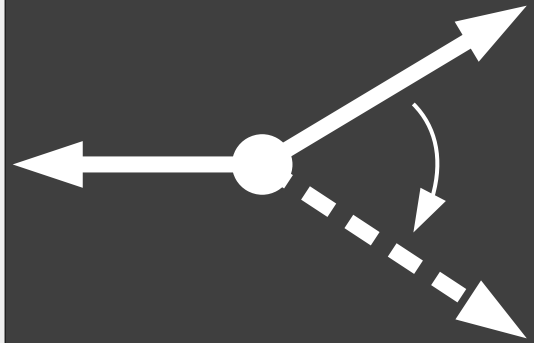
controlLab


controlLab


require 'capybara/rspec'
require 'capybara/rails'
Capybara.javascript_driver
Category.delete_all;
Shoulda::Matchers.
config.integrate
with.test_framework
with.library :rails
end
end
Add additional
Requires supporting
spec/support/ and its
run as spec files by
in _spec.rb will
run twice. It is
end with _spec.rb.
No results found for 'mongoid'
Coding standards
Design patterns
Modular design
...
controlLab


CS
Scenario 3 - Transferring a Full Hot Metal Ladle to the Desulph
Operator Guest
Camera
First Person
Overview Task
Hook engagement
Training
Pause
Stop Simulation
Alerts
Radio
Outside Flight Path
Collisions
Scenario Controls
In Bay
In Bay
Ladle Breakout
Ladle 1
Ladle 2
No Breakout
No Breakout
Upright Flare
Flare Position
Up
Torpedos
East
West
HM South
HM North
Developed for Tata Steel Port Talbot by BLUF and Controllab Projects.
Version 1.0.0

controllab



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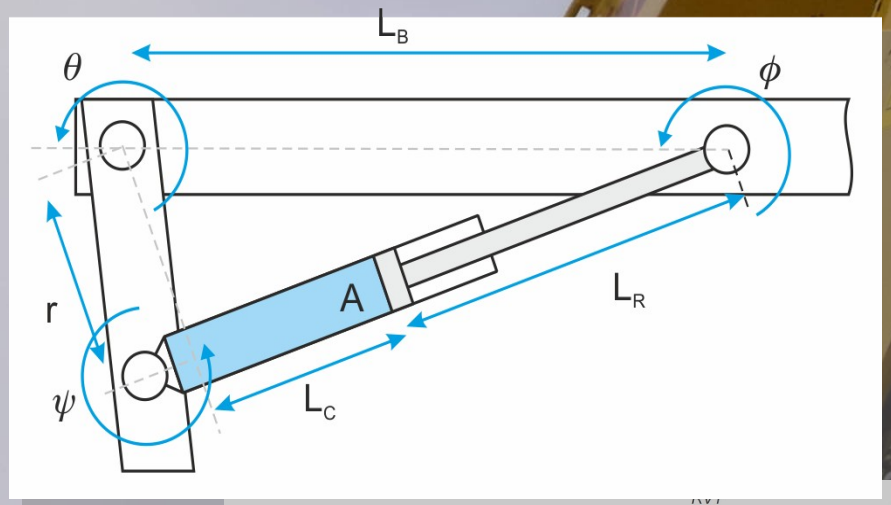
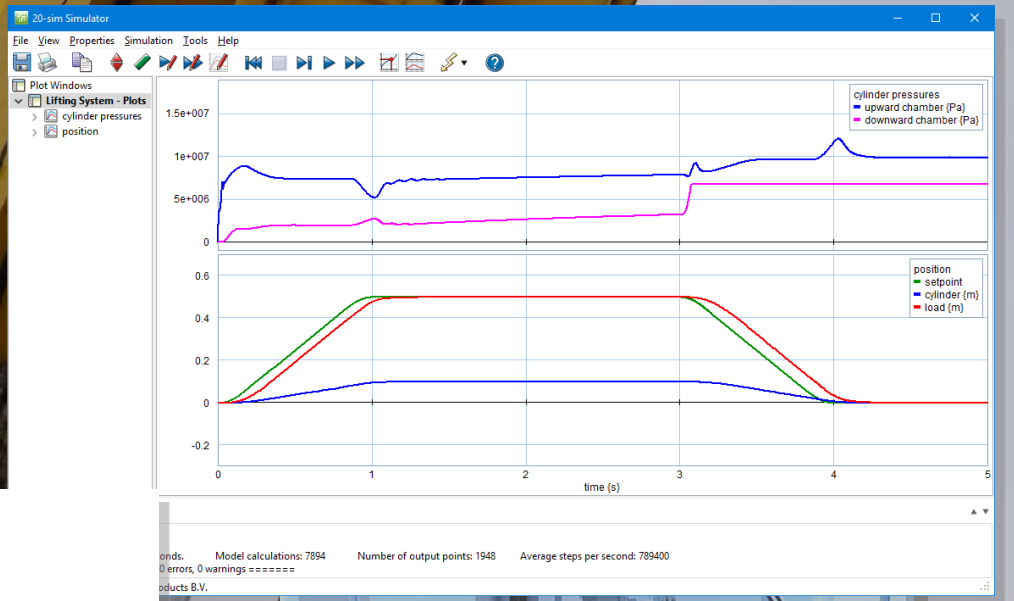
TEA TIME
PHILIPS
controlLab





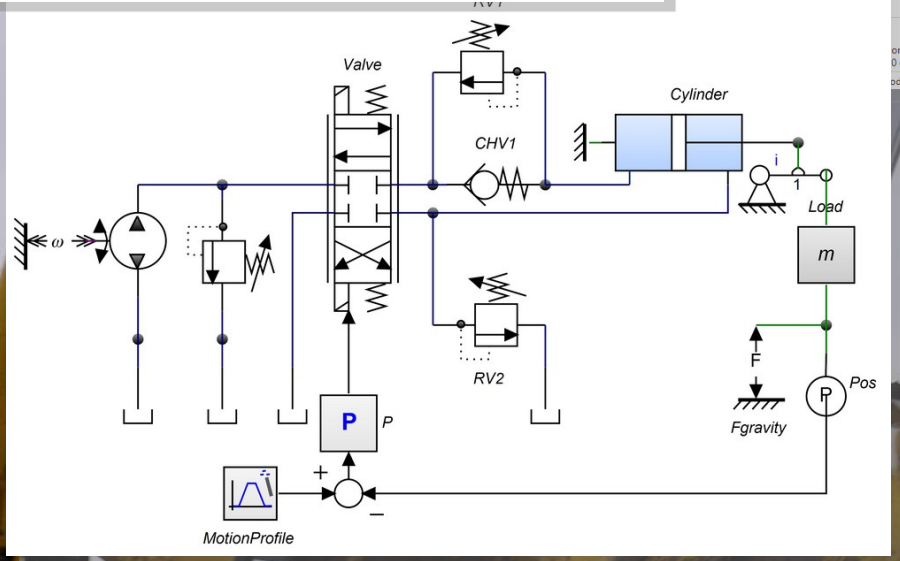
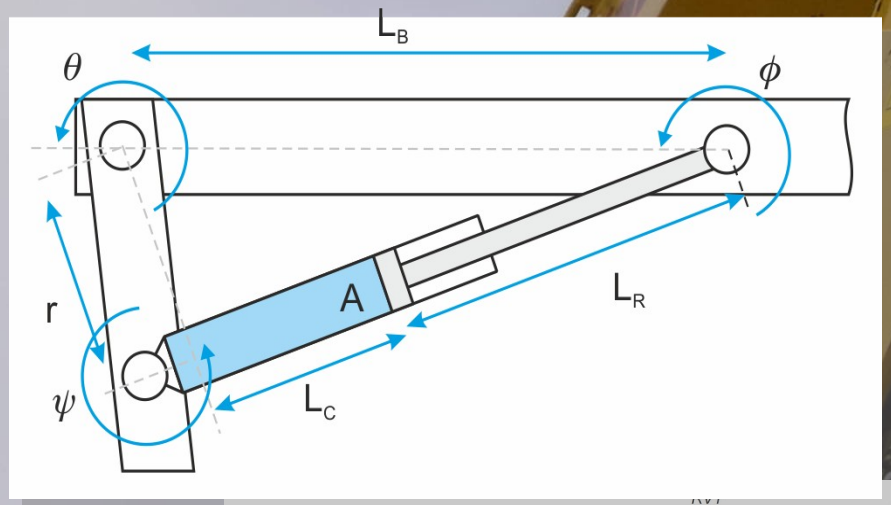
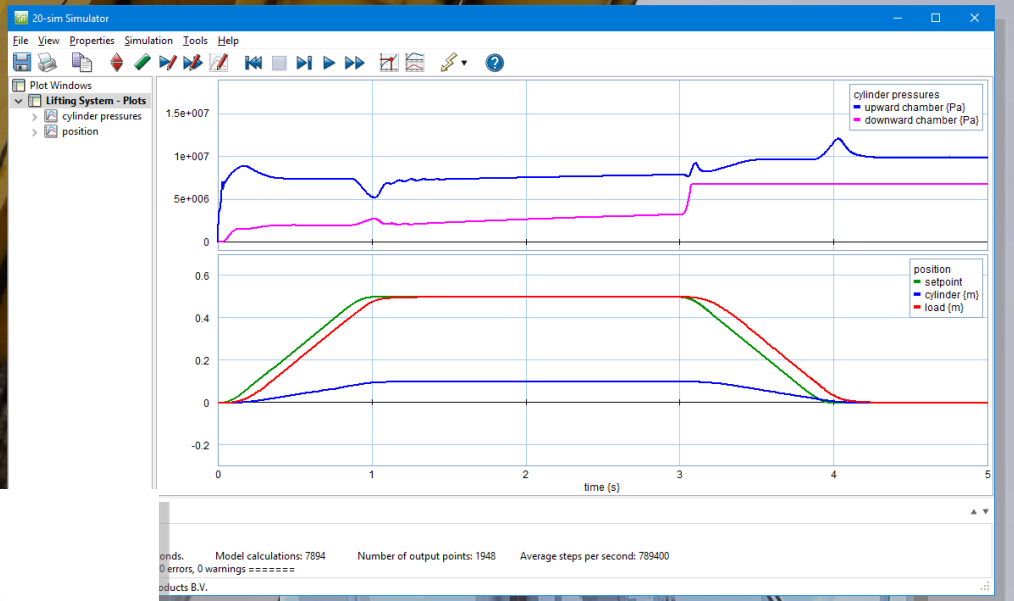


foto courtesy Jason Woodhead

controllab


multiped
Pump Control
Search signals, dashboards, tiles...
Pump Load
Power
Level
Load Distribution
Load Detail
Level Detail
Values
Load [%]
Level [%]
1m 5m 10m 1h 1D 1w 1M 1Y
31-03-2022 12:01:30 to 07-04-2022 12:01:3
controlLab





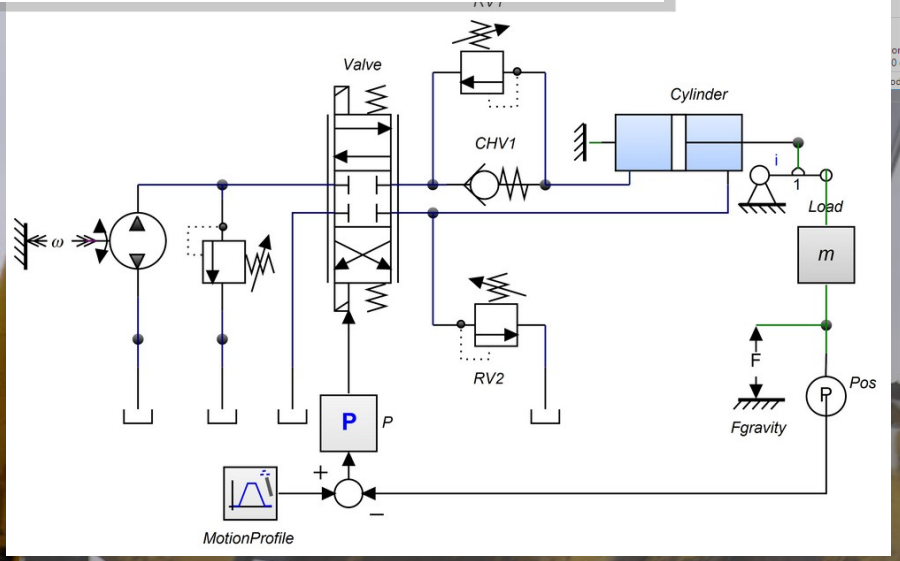


foto courtesy Jason Woodhead

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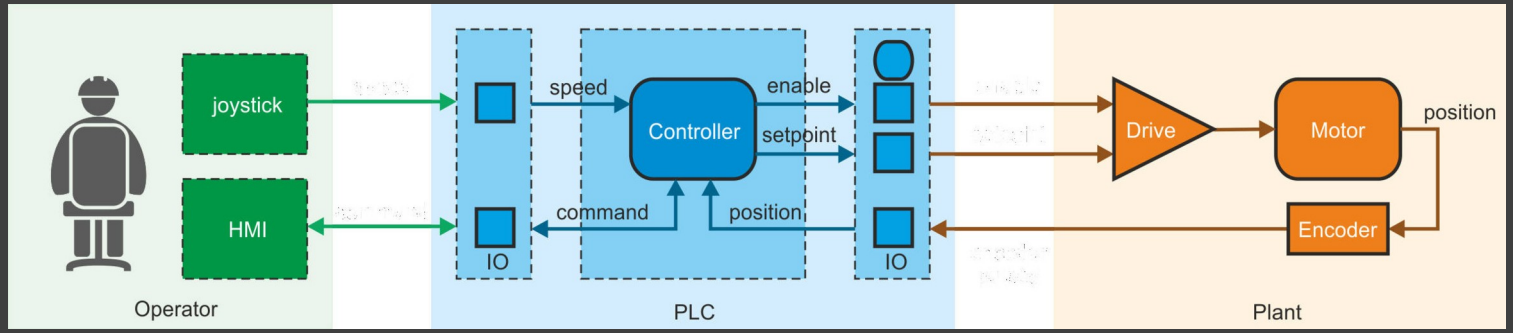
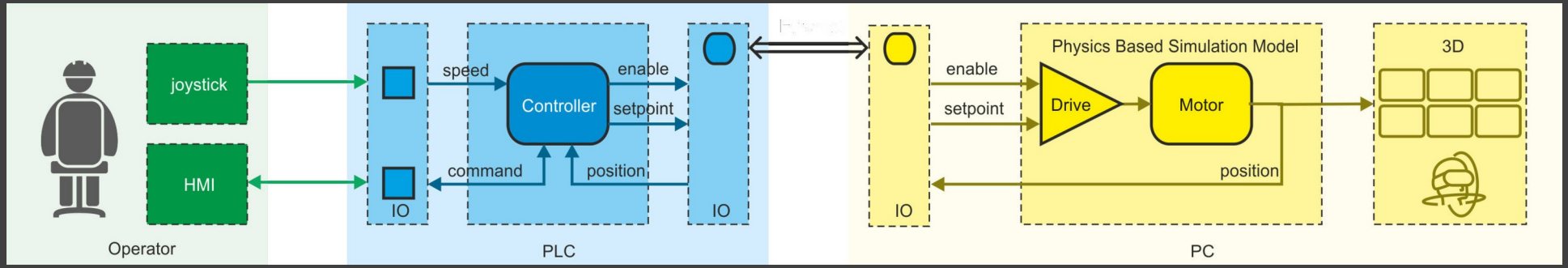
real machine



simulator



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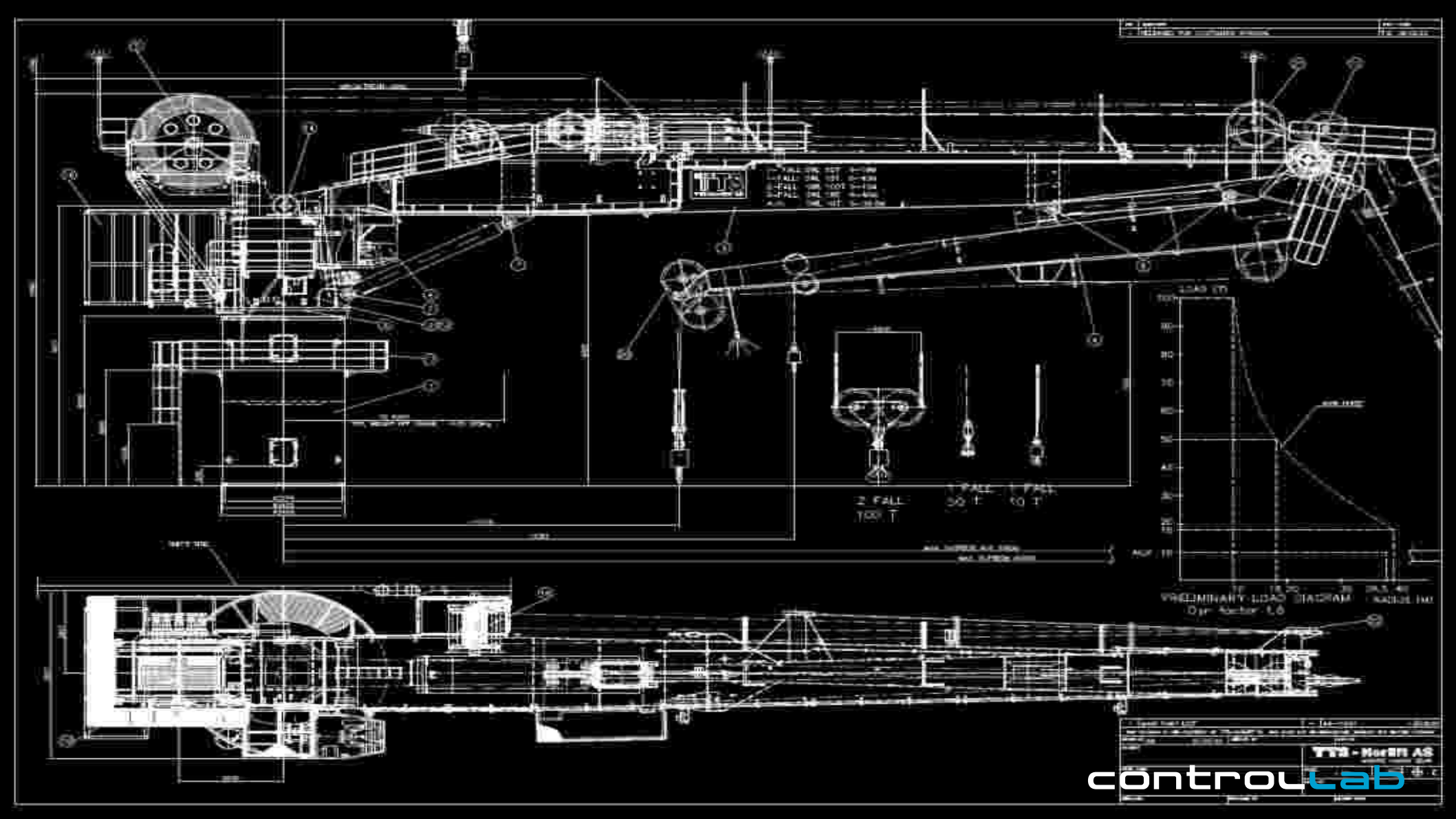
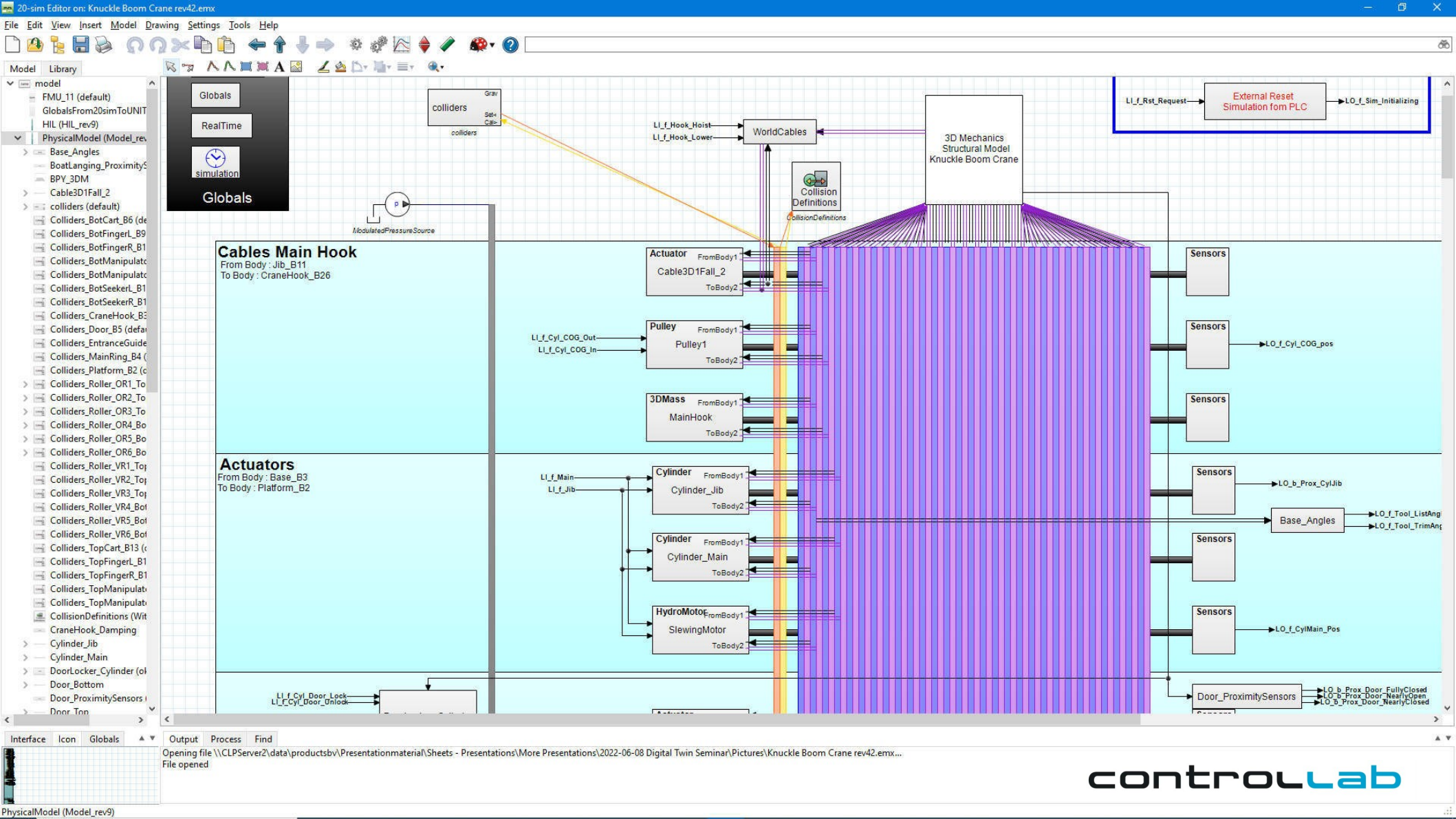
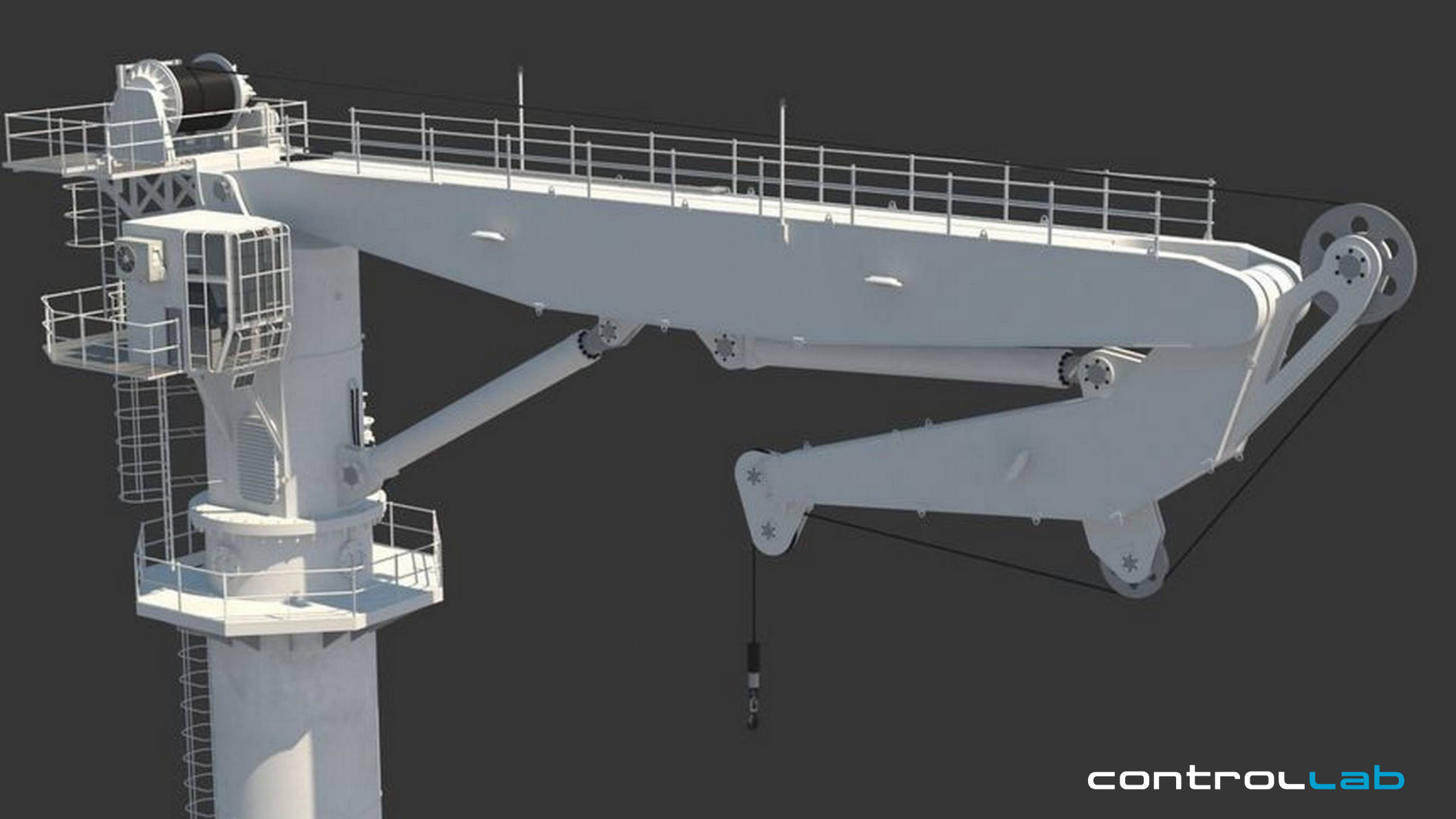
HIGHWIND BOOMLOCK DEMO
EliteDesk
controllab


2 FALL
100 T
1 FALL
50 T
1 FALL
10 T
PRELIMINARY LOAD DIAGRAM
Dyn factor 1.6
TTS - Norlift AS


20-sim Editor on: Knuckle Boom Crane rev42.emx
File Edit View Insert Model Drawing Settings Tools Help
Model Library
model
FMU_11 (default)
GlobalsFrom20simToUNIT
HIL (HIL_rev9)
PhysicalModel (Model_rev
Base_Angles
BoatLanging_ProximityS
BPY_3DM
Cable3D1Fall_2
colliders (default)
Colliders_BotCart_B6 (de
Colliders_BotFingerL_B9
Colliders_BotFingerR_B1
Colliders_BotManipulato
Colliders_BotManipulato
Colliders_BotSeekerL_B1
Colliders_BotSeekerR_B1
Colliders_CraneHook_B3
Colliders_Door_B5 (defa
Colliders_EntranceGuide
Colliders_MainRing_B4 (
Colliders_Platform_B2 (c
Colliders_Roller_OR1_To
Colliders_Roller_OR2_To
Colliders_Roller_OR3_To
Colliders_Roller_OR4_Bo
Colliders_Roller_OR5_Bo
Colliders_Roller_OR6_Bo
Colliders_Roller_VR1_To
Colliders_Roller_VR2_To
Colliders_Roller_VR3_To
Colliders_Roller_VR4_Bot
Colliders_Roller_VR5_Bot
Colliders_Roller_VR6_Bot
Colliders_TopCart_B13 (
Colliders_TopFingerL_B1
Colliders_TopFingerR_B1
Colliders_TopManipulato
Colliders_TopManipulato
CollisionDefinitions (Wit
CraneHook_Damping
Cylinder_Jib
Cylinder_Main
DoorLocker_Cylinder (ol
Door_Bottom
Door_ProximitySensors
Door_Top
Globals
RealTime
simulation
Globals
colliders
Grav
Set<
Call>
colliders
ModulatedPressureSource
LI_f_Hook_Hoist
LI_f_Hook_Lower
WorldCables
3D Mechanics
Structural Model
Knuckle Boom Crane
Collision
Definitions
CollisionDefinitions
LI_f_Rst_Request
External Reset
Simulation fom PLC
LO_f_Sim_Initializing
Cables Main Hook
From Body : Jib_B11
To Body : CraneHook_B26
Actuator
FromBody1
Cable3D1Fall_2
ToBody2
Sensors
Pulley
FromBody1
LI_f_Cyl_COG_Out
LI_f_Cyl_COG_In
Pulley1
ToBody2
Sensors
LO_f_Cyl_COG_pos
3DMass
FromBody1
MainHook
ToBody2
Sensors
Actuators
From Body : Base_B3
To Body : Platform_B2
LI_f_Main
LI_f_Jib
Cylinder
FromBody1
Cylinder_Jib
ToBody2
Sensors
LO_b_Prox_CylJib
Base_Angles
LO_f_Tool_ListAng
LO_f_Tool_TrimAng
Cylinder
FromBody1
Cylinder_Main
ToBody2
Sensors
HydroMotor
FromBody1
SlewingMotor
ToBody2
Sensors
LO_f_CylMain_Pos
LI_f_Cyl_Door_Lock
LI_f_Cyl_Door_Unlock
Door_ProximitySensors
LO_b_Prox_Door_FullyClosed
LO_b_Prox_Door_NearlyOpen
LO_b_Prox_Door_NearlyClosed
Interface Icon Globals
Output Process Find
Opening file \\CLPServer2\data\productsbv\Presentationmaterial\Sheets - Presentations\More Presentations\2022-06-08 Digital Twin Seminar\Pictures\Knuckle Boom Crane rev42.emx...
File opened
controlLab
PhysicalModel (Model_rev9)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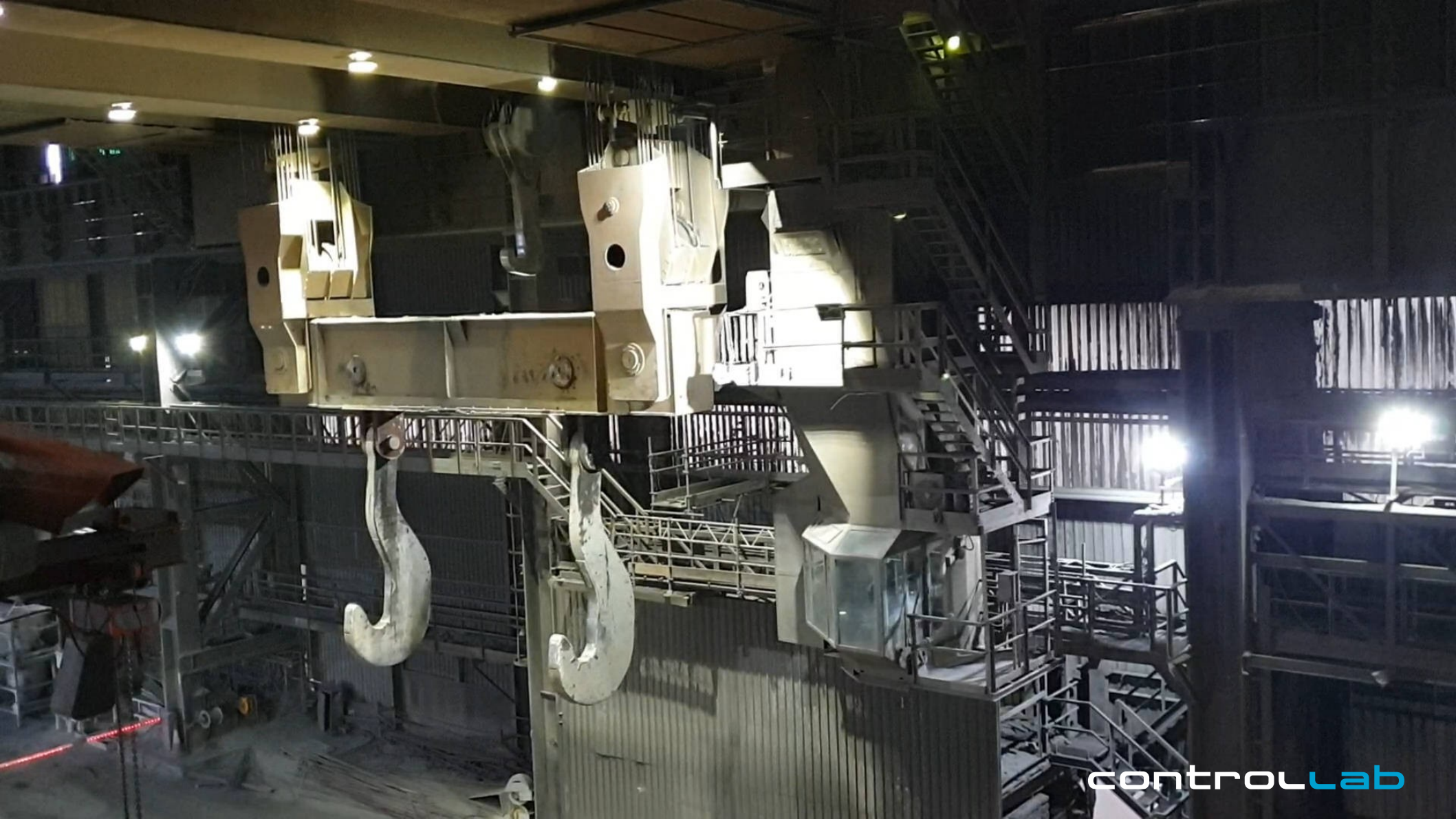
Slewing :
Luffing :
Knuckling :
Cable Length :
Wind Speed :
In Range :
13.82
CAM01
Winch
DOWN
Luffing
DOWN
Motion
Compensation


controlLab


controlLab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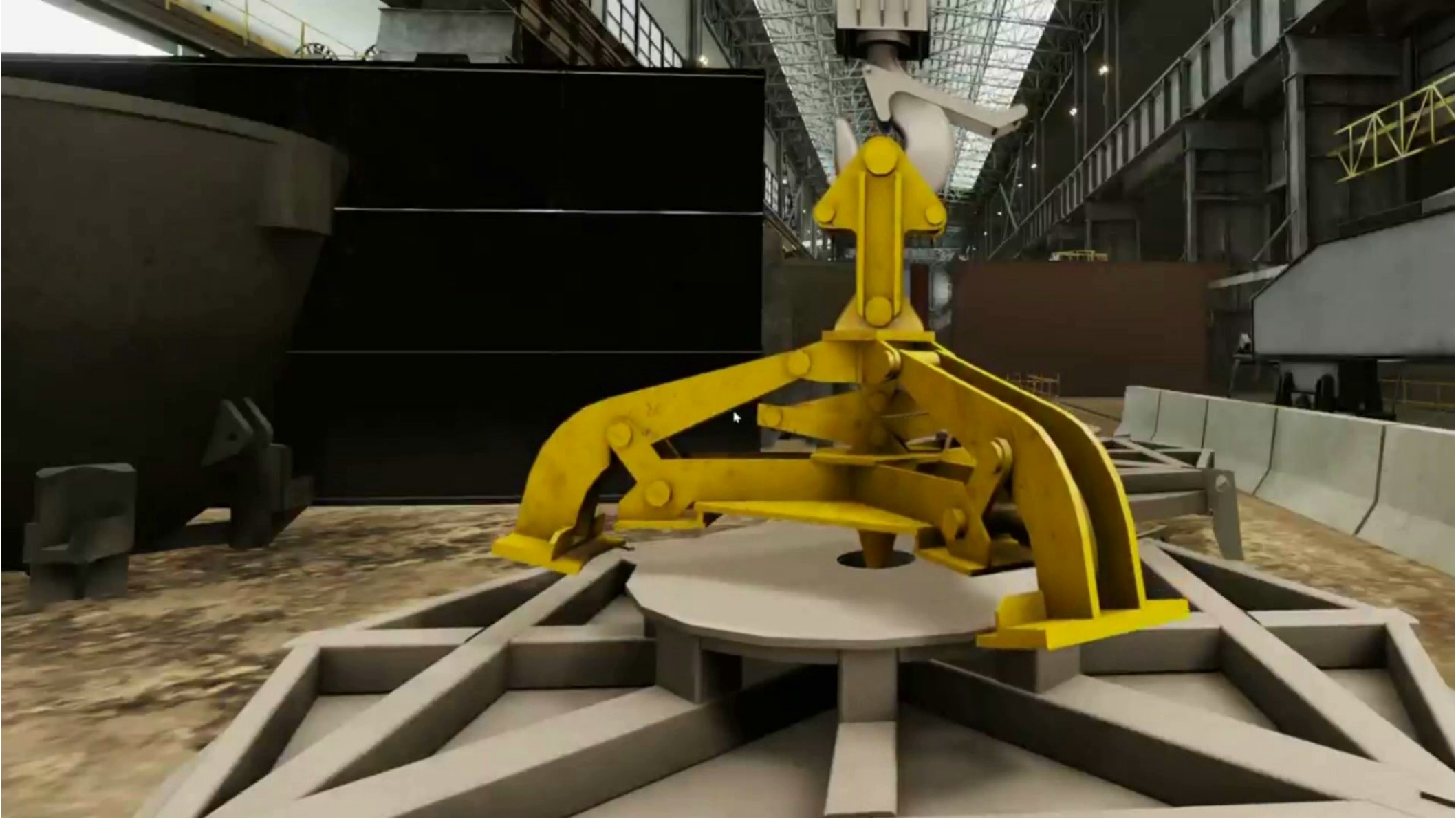
CS
Scenario 5 - Decanting a Hot Metal Ladle
Camera
First Person
Overview Task
Hook engagement
Developed for Tata Steel Port Talbot by BLUF and Controllab Projects.
Training
Pause
Stop Simulation
Alerts
Radio
Outside Flight Path
0
Collisions
3
Scenario Controls
Converter North
Angle
Charging Iron
Traffic Light
Red
Converter South
Angle
Charging Iron
Traffic Light
Red
Desulph North
Hood
Parked
Lance
In
Desulph South
Hood
controllab



Digitale Tweelingen

betere en veiliger software

beter opgeleide mensen

kosten besparen

controlLab